

Angular Differential Imaging with Microwave Kinetic Inductance Detectors

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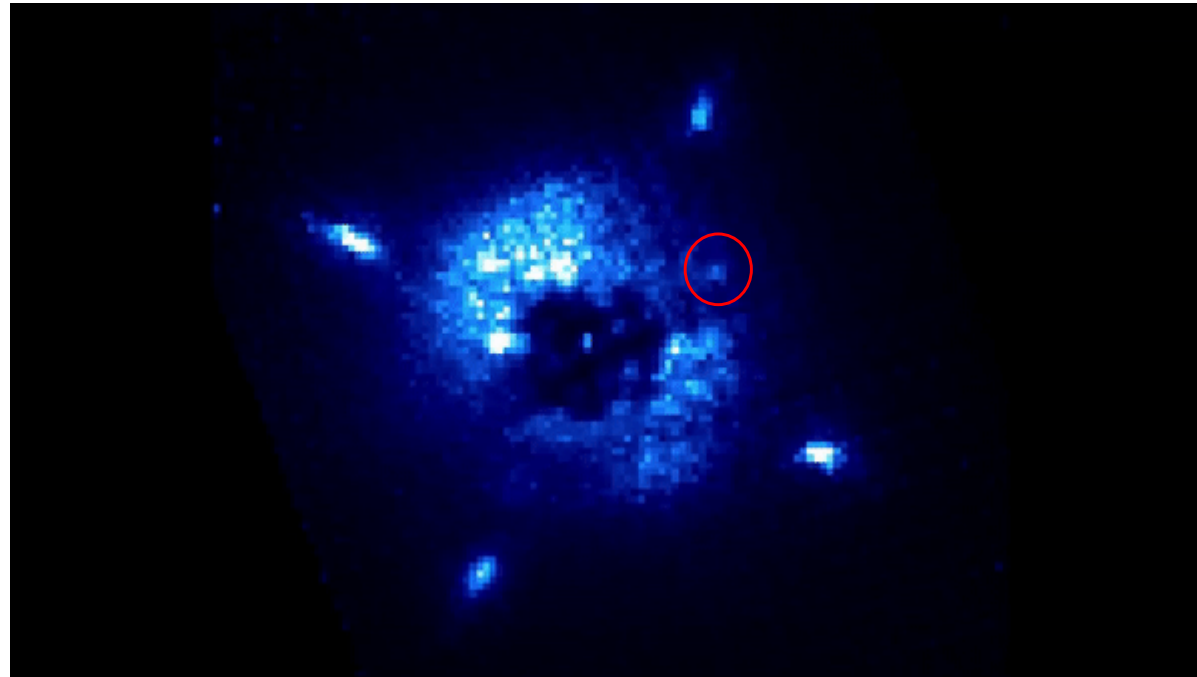
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Outline

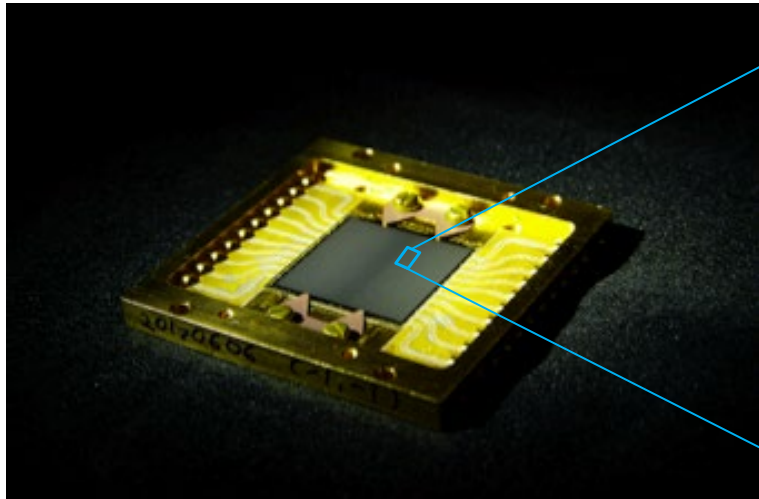
- Emergence of Exoplanet Astronomy
- What is an MKID?
- MKID Pipeline
- Angular Differential Imaging
- Results
- Future Work

Are we alone?



Wavelength scan of star (behind coronagraph) and companion (circled) from MEC

What is an MKID?

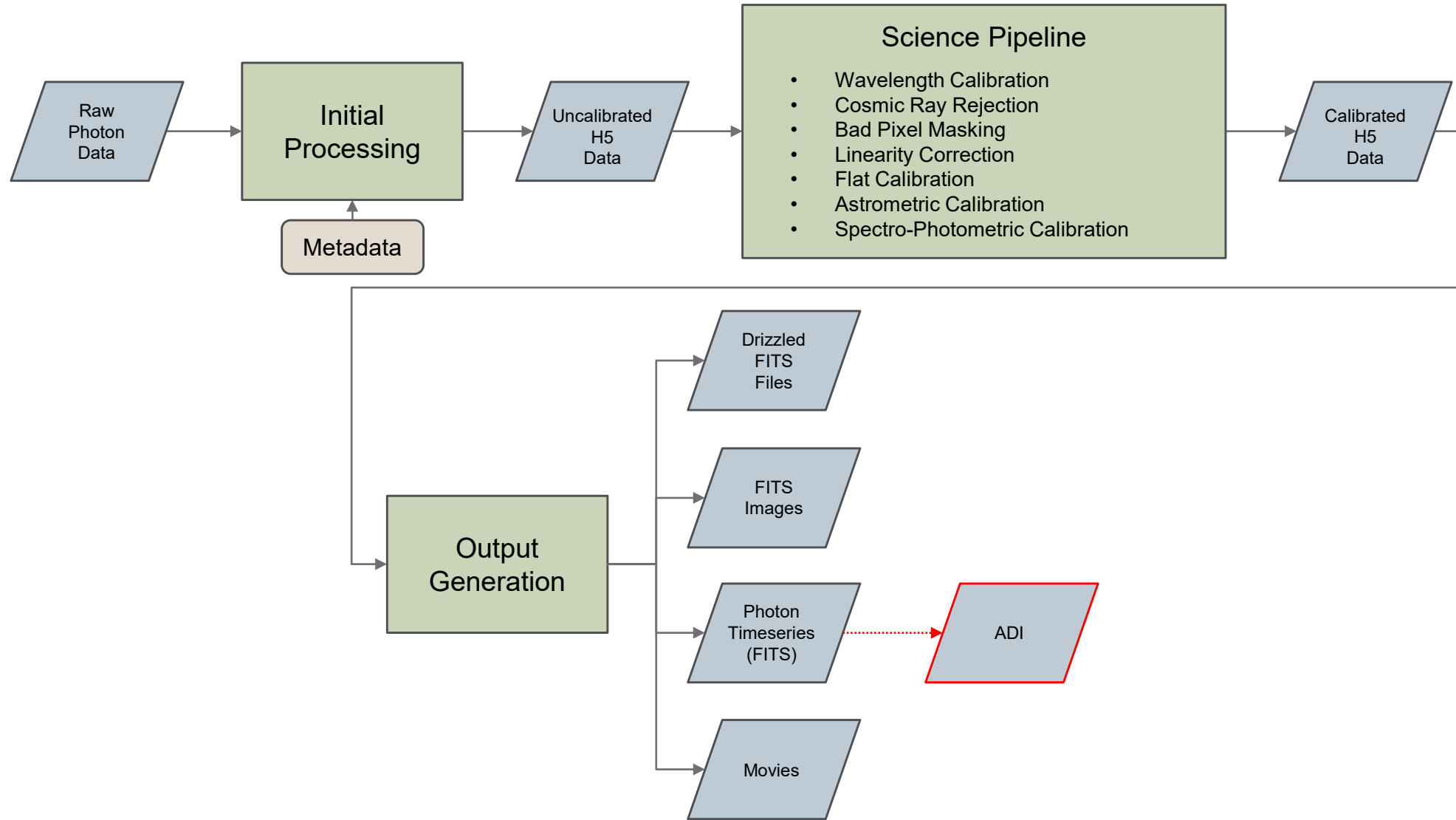


~20,000 pixel MKID array used in MEC

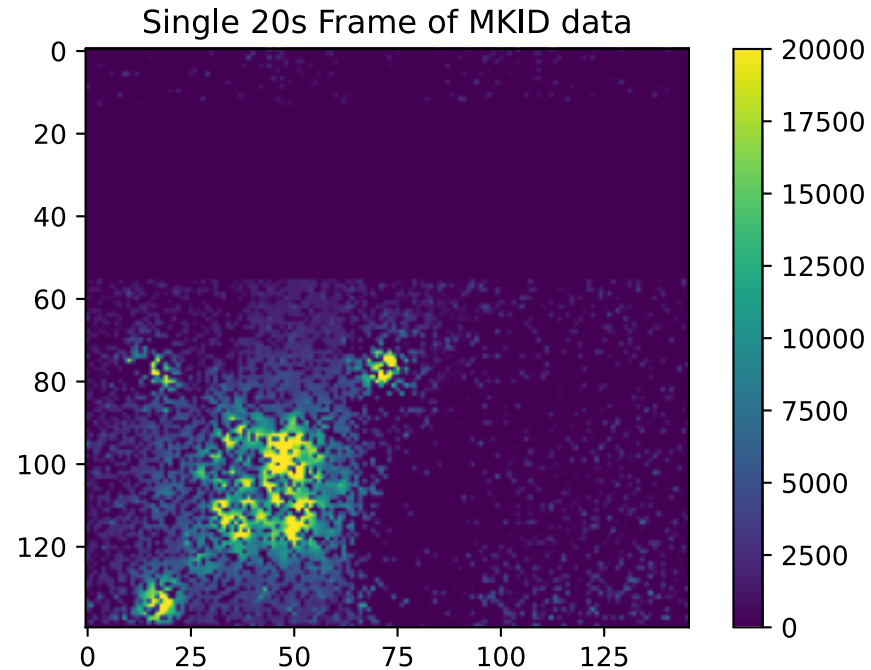


Microscopic view of individual MKIDs (pixels)

MKID Pipeline



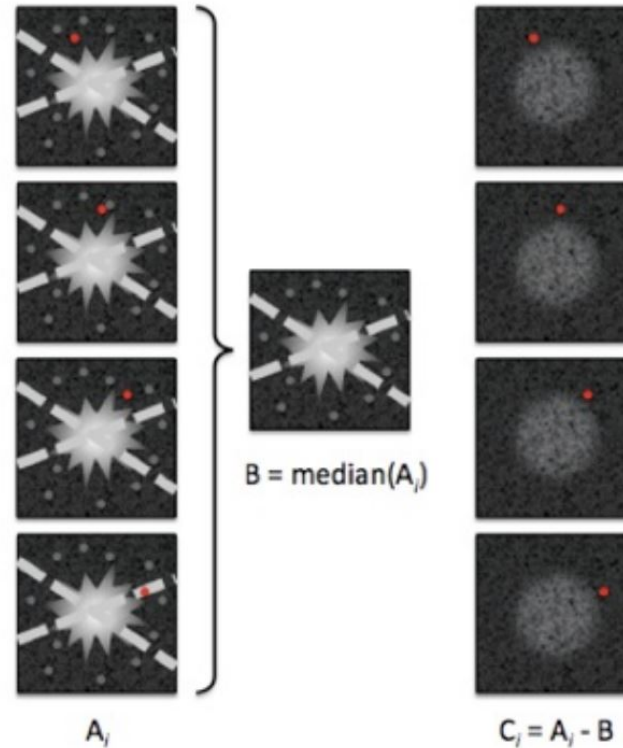
Angular Differential Imaging (ADI)



Typical reduced image of a target with speckle halo and satellite spots

Classical ADI Algorithm

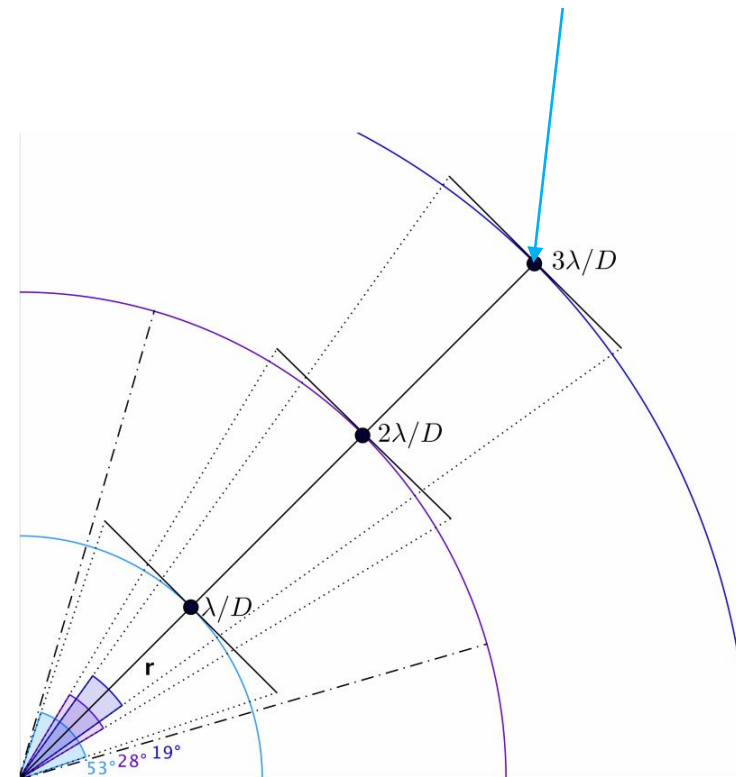
First phase: Find a reference PSF image from all frames in the set and subsequently subtract that reference from all frames.



Classical ADI Algorithm

Frame that will have localized reference PSF generated, with FOV rotation amount θ

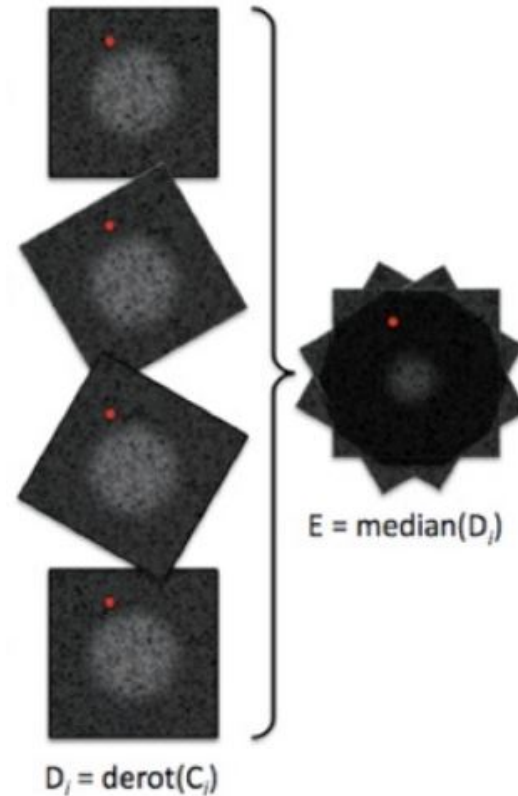
Second phase: Find a **localized, annular** reference PSF image for **each** frame in the set and subsequently subtract that reference from it's related frame.



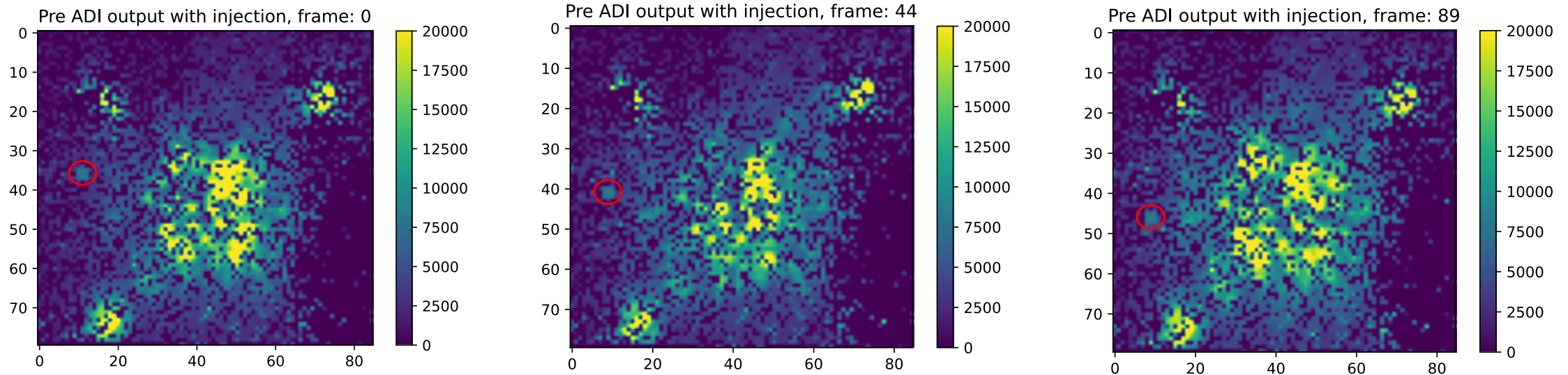
Reference frame exclusion zones, as a function of annulus separation. Excludes frames that have less than 1.5 FWHM displacement.

Classical ADI Algorithm

Final phase: De-rotate all frames in the set such that their orientations align with the initial frame and then perform median combination

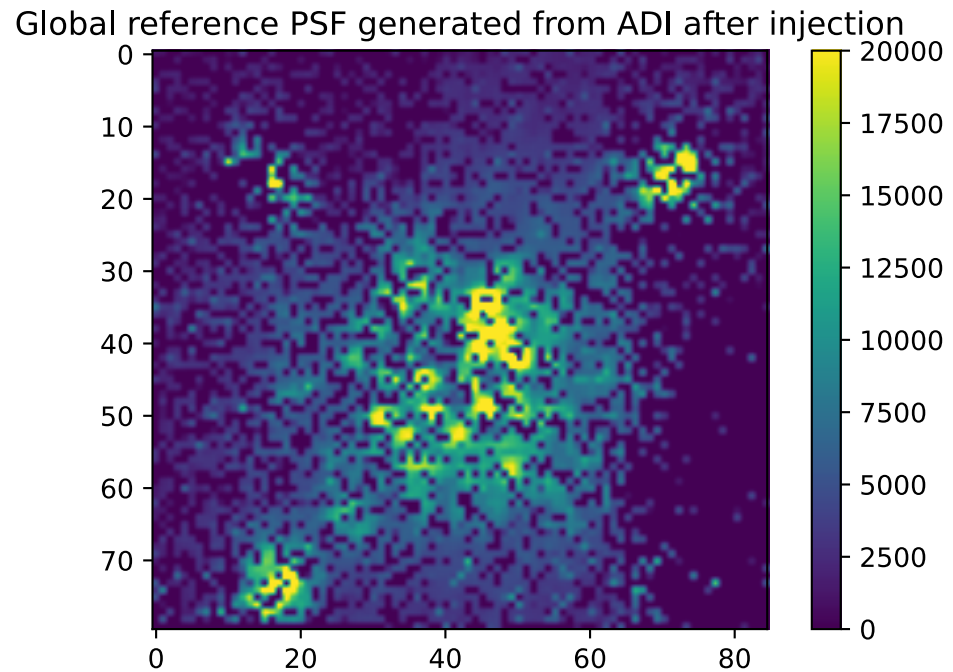


Companion Injection: Pre-ADI



- Companion injected at 0.25" separation
- ~20 degrees of total FOV rotation

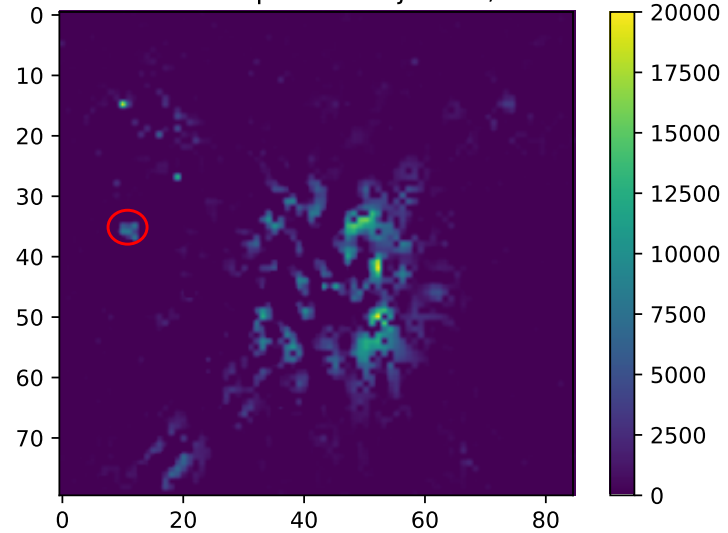
Global Reference PSF



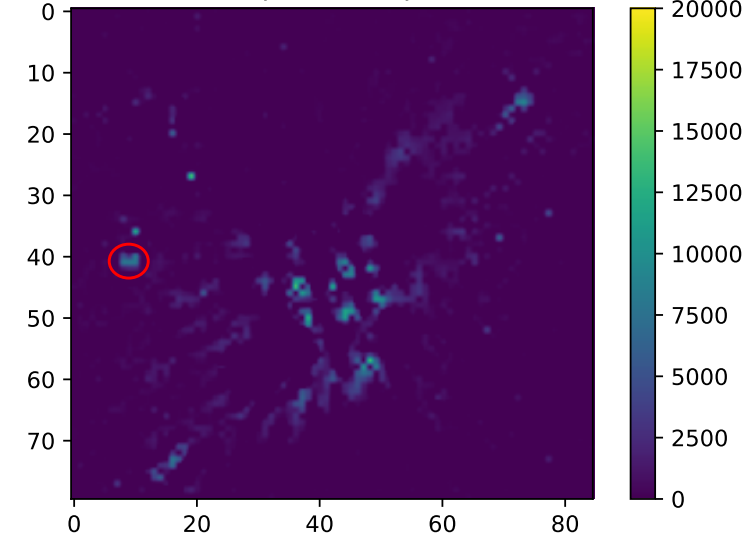
Signature of the injected companion is missing from the reference PSF

Companion Injection: Post-ADI

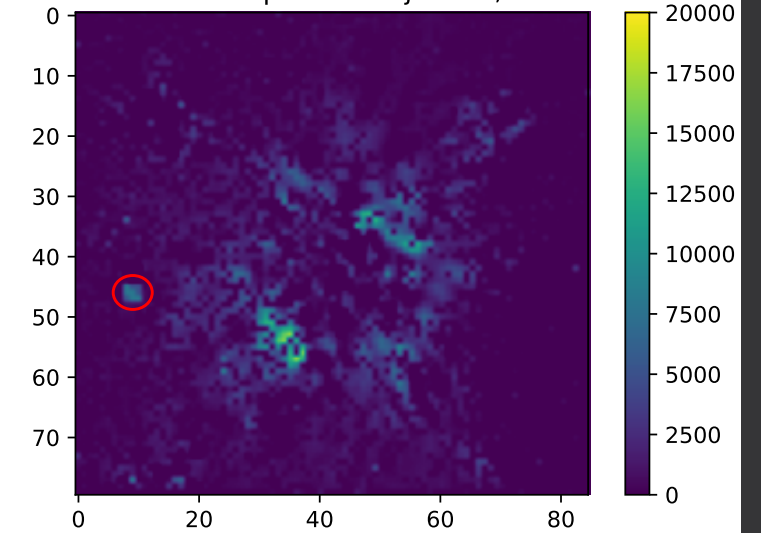
Unrotated ADI output with injection, frame: 0



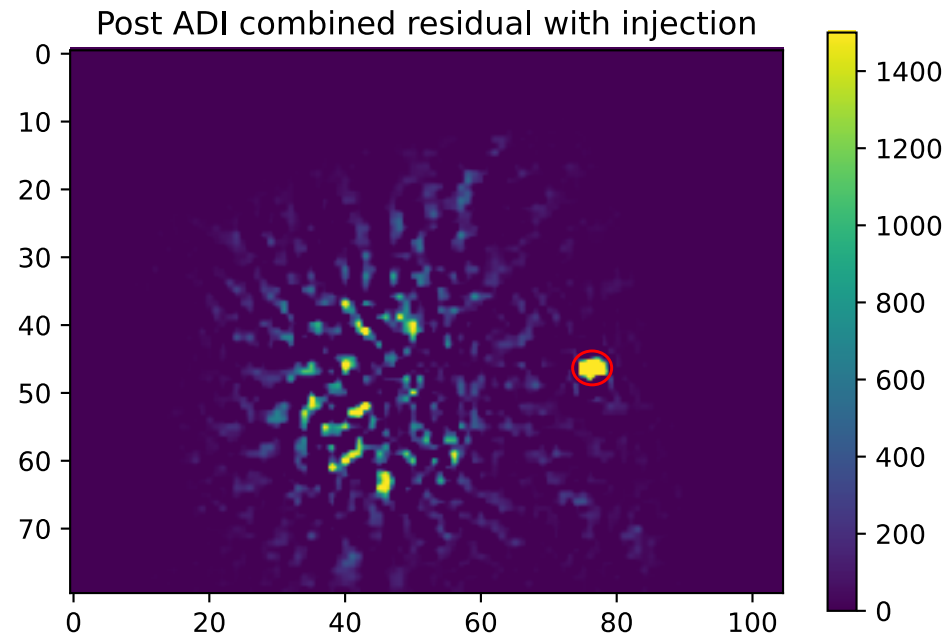
Unrotated ADI output with injection, frame: 44



Unrotated ADI output with injection, frame: 89



Final Result



Future Work

- Engineer tighter integration with the MKID Pipeline
- Use the implementation to hunt for real companions in this dataset and datasets from other candidate targets!

Acknowledgments

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